

Dev. Track			
	Name(s)	Title	Number
	Masato Kubotera and Yasuo Hayashibara	<i>SUSTAINA-OP: Kid-sized Open Hardware Platform Humanoid Robot</i>	7358
	Graziano Specchi, Vincenzo Suriani, Michele Brienza, Francesco Laus, Flavio Maiorana, Andrea Pennisi, Daniele Nardi and Domenico Daniele Bloisi	<i>Structural Pruning for Real-Time Multi-Object Detection on NAO Robot</i>	720
	Nico Bohlinger and Klaus Dorer	<i>RL-X: A Deep Reinforcement Learning Library (not only) for RoboCup</i>	1317
	Eunsoo Chung, Haewon Jung, Yeonghun Chun, Wonyong Lee, Jangwon Lee, Minsung Ahn and Jeakweon Han	<i>Swing foot pose control disturbance overcoming algorithm based on reference ZMP preview controller for improving humanoid walking stability</i>	8472
	Louis Li, Maëlic Neau, Thomas Ung and Cédric Buche	<i>Crossing Real and Virtual : Pepper Robot as an Interactive Digital Twin</i>	6274